

Some results on BSDEs and related HJB equations

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PLAN

1. Statement of the problem.
2. HJB equations with superquadratic hamiltonian: lipschitz continuous final datum.
3. HJB equations with quadratic hamiltonian: continuous final datum.
4. Application to stochastic optimal control.

PDE in an infinite dimensional Hilbert space H

$$\begin{cases} \frac{\partial v}{\partial t}(t, x) = -\mathcal{L}v(t, x) + \psi(\nabla v(t, x) \sqrt{Q}) + l(x), & t \in [0, T], x \in H \\ v(T, x) = \phi(x), \end{cases}$$

$$(\mathcal{L}f)(x) = \frac{1}{2}(\text{Tr}Q\nabla^2 f)(x) + \langle Ax, \nabla f(x) \rangle.$$

\mathcal{L} generator of the transition semigroup P_t of the Ornstein-Uhlenbeck process

$$\begin{cases} dX_t = AX_t dt + \sqrt{Q}dW_t, & t \in [0, T] \\ X_0 = x. \end{cases}$$

F. Gozzi, Global regular solutions of second order Hamilton-Jacobi equations in Hilbert spaces with locally Lipschitz nonlinearities, JMAA 1996.

X. Bao, F. Delbaen and Y. Hu, Backward SDEs with superquadratic growth, arXiv:0902.3316, to appear on PTRF.

Assumptions on A, Q, P_t .

1. A generator of a C_0 semigroup $(e^{tA}, t \geq 0)$ in H . $\exists M \geq 1, \omega \geq 0$ s.t. $\|e^{tA}\|_{L(H,H)} \leq Me^{\omega t}$.
2. $\sqrt{Q} : H \rightarrow H$ and $Q_\sigma := \int_0^\sigma e^{sA} Q^* e^{sA} ds$ of trace class $\forall \sigma \geq 0$.
3. regularizing property for P_t : for some $\alpha \in [0, 1)$ and $\forall \phi \in C_b(H), \exists c > 0$ s.t. $\forall \xi \in H$ and for $0 \leq t < \tau \leq T$,

$$\left| \nabla P_\tau [\phi] (x) \sqrt{Q} \xi \right| \leq \frac{c}{\tau^\alpha} \|\phi\|_\infty |\xi|$$

4. A and Q commute: point 3 holds true with $\alpha = 1/2$.

see F. M., Semilinear Kolmogorov equations and applications to stochastic optimal control, AMO 2005.

Linear heat equation

$\mathcal{O} \in \mathbb{R}$, $H = L^2(\Omega)$, $\{e_k\}_{k \in \mathbb{N}}$ complete orthonormal basis diagonalizing Δ , endowed with Dirichlet boundary conditions in \mathcal{O} .

$$\begin{cases} \frac{\partial y}{\partial s}(s, \xi) = \Delta y(s, \xi) + \frac{\partial W^Q}{\partial s}(s, \xi), & s \in [t, T], \xi \in \mathcal{O}, \\ y(t, \xi) = x(\xi), \\ y(s, \xi) = 0, & \xi \in \partial\mathcal{O}. \end{cases}$$

$W^Q(s, \xi)$ Gaussian mean zero random field, with covariance given by

$$\mathbb{E} \langle W^Q(s, \cdot), h \rangle_H \langle W^Q(t, \cdot), k \rangle_H = t \wedge s \langle Qh, k \rangle_H .$$

• $Q : H \rightarrow H$ positive, $Qe_k = \lambda_k e_k$, $k \in \mathbb{N}$, formally $W^Q(s, \cdot) = \sum_{k \geq 0} Qe_k(\cdot) \beta_k(s)$.
with $\{\beta_k(s)\}_{k \in \mathbb{N}}$ independent Brownian motions.

“Abstract” formulation of the heat equation

$$\begin{cases} dX_\tau = AX_\tau d\tau + \sqrt{Q}dW_\tau, & \tau \in [t, T] \\ X_t = x. \end{cases}$$

HJB equations with superquadratic hamiltonian

$$\begin{cases} \frac{\partial v}{\partial t}(t, x) = -\mathcal{L}v(t, x) + \psi(\nabla v(t, x) \sqrt{Q}) + l(x), & t \in [0, T], x \in H \\ v(T, x) = \phi(x). \end{cases}$$

Hypothesis $\psi : H \rightarrow \mathbb{R}$, is Gâteaux differentiable and for every $\xi_1, \xi_2 \in H$, $|\psi(\xi_1) - \psi(\xi_2)| \leq (1 + |\xi_1|^{p-1} + |\xi_2|^{p-1})|\xi_1 - \xi_2|$, for $p \geq 2$.

Mild solution $v \in C_b([0, T] \times H, \mathbb{R})$ s.t. $|\nabla v(t, x) \sqrt{Q}| \leq Ct^{-\alpha}$ satisfying

$$v(t, x) = P_{t,T}[\phi](x) - \int_t^T P_{t,s} \left[\psi(\nabla v(s, \cdot) \sqrt{Q}) \right] (x) ds, - \int_t^T P_{t,s} [l](x) ds.$$

From now on we present results in the case $l = 0$ and $\psi(0) = 0$.

Related forward-backward SDE (FBSDE)

$$\begin{cases} dX_\tau = AX_\tau d\tau + \sqrt{Q}dW_\tau, & \tau \in [t, T] \subset [0, T], \\ X_t = x, \\ dY_\tau = -\psi(Z_\tau) d\tau + Z_\tau dW_\tau, \\ Y_T = \phi(X_T). \end{cases}$$

Let us also denote $(X, Y, Z) = (X^{t,x}, Y^{t,x}, Z^{t,x})$.

Connection between BSDEs and HJBs

If v solve HJB equation, then $(X_\tau^{t,x}, v(\tau, X_\tau^{t,x}), \nabla v(\tau, X_\tau^{t,x}))$ solve FBSDE.

Viceversa if $(X^{t,x}, Y^{t,x}, Z^{t,x})$ solve the FBSDE then $v(t, x) := Y_t^{t,x}$ is mild solution to HJB, provided $Z_t^{t,x} = \nabla_x Y_t^{t,x} \sqrt{Q}$.

E. Pardoux, S. Peng, Adapted solution of a backward stochastic differential equation, Systems and Control Lett. 1990.

M. Fuhrman, G. Tessitore, Nonlinear Kolmogorov equations in infinite dimensional spaces: the backward stochastic differential equations approach and applications to optimal control. AoP 2002.

Theorem 1 *If the previous assumptions on A , Q and ψ hold true, and if ϕ is bounded and lipschitz continuous, then equation*

$$\begin{cases} dY_\tau = -\psi(Z_\tau) d\tau + Z_\tau dW_\tau, \\ Y_T = \phi(X_T), \end{cases}$$

admits a unique solution. The function $v(t, x) = Y_t^{t,x}$ is the unique mild solution of the HJB equation

Sketch of the proof. At first we assume further that ϕ is Gâteaux differentiable with bounded derivative.

- Local mild solution on $[T - \delta, T]$ s.t., due to the regularity of ϕ , $\nabla v(t, x)\sqrt{Q}$ does not blow up: namely

$$|v(t, x)| + \|\nabla v(t, x)\sqrt{Q}\| \leq 2Me^{\omega T} \|\phi\|_1$$

- Equivalent representation of the mild solution:

$$v(t, x) = R_{t,T} [\phi] (x), \quad t \in [T - \delta, T], \quad x \in H.$$

Set $G(t, x) = \int_0^1 \nabla \psi(\lambda \nabla \sqrt{Q} v(t, x)) d\lambda$.

$R_{t,\tau}$ transition semigroup of $\Theta^{t,x}$, solution to

$$\begin{cases} d\Theta_\tau^{t,x} = A\Theta_\tau^{t,x} d\tau + \sqrt{Q}G(\tau, \Theta_\tau^{t,x})d\tau + \sqrt{Q}dW_\tau, & \tau \in [t, T] \quad t \in [T - \delta, T] \\ \Theta_t = x, \end{cases}$$

- A priori estimates: by the equivalent representation v is bounded. By the connection with BSDEs we also get $\nabla v \sqrt{Q}$ is bounded.
- Global existence follows by local existence and a priori estimates.
- ϕ bounded and Lipschitz continuous: let the inf-sup convolution of ϕ

$$\phi_n(x) = \sup_{z \in H} \left\{ \inf_{y \in H} \left[\phi(y) + n \frac{|z - y|_H^2}{2} \right] - n |x - z|_H^2 \right\}$$

L Lipschitz constant of $\phi \Rightarrow |\nabla \phi_n| \leq L$.

Aim: solve the HJB equation with quadratic hamiltonian ψ and with final datum ϕ bounded and continuous. Fundamental assumption: A and Q commute.

- In the case of Gâteaux differentiable final datum ϕ find an estimate for the $\nabla v(t, x)\sqrt{Q}$ depending on $T, t, \|\phi\|_\infty$ but not on $\nabla\phi$:

$$|\nabla v(t, x)\sqrt{Q}\xi| \leq C(T - t)^{-1/2}.$$

BMO martingales technique and a new Bismut-Elworthy formula, see

X. Bao, F. Delbaen and Y. Hu, and

A. Richou, Numerical simulation of BSDEs with drivers of quadratic growth, arXiv:1001.0401.

- ϕ bounded and continuous: approximation procedure on ϕ by means of its inf-sup convolutions $(\phi_n)_n$.

$$\begin{cases} \frac{\partial v}{\partial t}(t, x) = -\mathcal{L}v(t, x) + \psi(\nabla v(t, x) \sqrt{Q}) + l(x), & t \in [0, T], x \in H \\ v(T, x) = \phi(x). \end{cases}$$

$$\begin{cases} dX_\tau = AX_\tau d\tau + \sqrt{Q}dW_\tau, & \tau \in [t, T] \subset [0, T], \\ X_t = x, \\ dY_\tau = -\psi(Z_\tau) d\tau + Z_\tau dW_\tau, \\ Y_T = \phi(X_T^{t,x}). \end{cases}$$

Hypothesis $\psi : H \rightarrow \mathbb{R}$, is Gâteaux differentiable and for every $\xi_1, \xi_2 \in \Xi$, $|\psi(\xi_1) - \psi(\xi_2)| \leq (1 + |\xi_1| + |\xi_2|)|\xi_1 - \xi_2|$.

Theorem 2 Let (Y, Z) be the solution of the BSDE. If A, Q, ψ satisfy the previous assumptions, and if ϕ is differentiable then the following estimate holds true:

$$|Z_t^{t,x}| \leq C \|\phi\|_\infty (T - t)^{-1/2},$$

where C depends on t, T, A and not on $\nabla \phi$. Moreover $Z_t^{t,x} = \nabla v(t, x) \sqrt{Q}$.

Sketch of the proof. $(\Phi(\tau) = \int_t^\tau Z_s dW_s)_{\tau \in [t, T]}$ BMO martingale

$$\|\Phi\|_{BMO} = \sup_{\sigma \in [t, T]} \mathbb{E} \left[\int_\sigma^T Z_s^2 ds \mid \mathcal{F}_\sigma \right]^{1/2} < +\infty,$$

$$F_\tau^{t,x} = \nabla Y_\tau^{t,x} \sqrt{Q} h \text{ and } V_\tau^{t,x} = \nabla Z_\tau^{t,x} \sqrt{Q} h.$$

$$\begin{cases} dF_\tau^{t,x} = -\nabla \psi(Z_\tau^{t,x}) V_\tau^{t,x} d\tau + V_\tau^{t,x} dW_\tau, \\ F_T^{t,x} = \nabla \phi(X_T^{t,x}) e^{(T-t)A} \sqrt{Q} h, \end{cases}$$

\mathbb{Q} s.t. $W_\tau^{\mathbb{Q}} := -\int_0^\tau \nabla \psi(Z_s^{t,x}) ds + W_\tau$ is a Wiener process.

$(\int_t^\tau \nabla \psi(Z_s^{t,x}) dW_s)_{\tau \in [t, T]}$ BMO martingale

$$\mathcal{E}_\tau = \exp \left(\int_t^\tau \psi(Z_s^{t,x}) W_s - \frac{1}{2} \int_t^\tau |\psi(Z_s^{t,x})|^2 ds \right),$$

is a uniformly integrable martingale.

In $(\Omega, \mathcal{F}, \mathbb{Q})$, $F^{t,x}$ is a martingale, so $(F^{t,x})^2$ is a \mathbb{Q} -submartingale.

So

$$\mathbb{E}^{\mathbb{Q}} \left[\int_t^T |F_s^{t,x}|^2 ds | \mathcal{F}_t \right] \geq |F_t^{t,x}|^2 (T - t) = |Z_t^{t,x} h|^2 (T - t).$$

A and Q commute,

$$\begin{aligned} F_{\tau}^{t,x} &:= \langle \nabla v(\tau, X_{\tau}^{t,x}), \sqrt{Q}h \rangle = \langle \nabla_x v(\tau, X_{\tau}^{t,x}), e^{(\tau-t)A} \sqrt{Q}h \rangle \\ &= \langle \nabla_x v(\tau, X_{\tau}^{t,x}), \sqrt{Q}e^{(\tau-t)A}h \rangle = \langle Z_{\tau}^{t,x}, e^{(\tau-t)A}h \rangle. \end{aligned}$$

Moreover

$$\mathbb{E}^{\mathbb{Q}} \left[\int_t^T |F_s^{t,x}|^2 ds | \mathcal{F}_t \right] = \mathbb{E}^{\mathbb{Q}} \left[\int_t^T | \langle Z_s^{t,x}, e^{(s-t)A}h \rangle |^2 ds | \mathcal{F}_t \right] \leq C_{t,T},$$

where $C_{t,T}$ depends only on T, t, A . So

$$|Z_t^{t,x}| \leq C(T - t)^{-1/2},$$

where C depends on $t, T, A, \|\phi\|_{\infty}$ and not on $\nabla\phi$.

Approximation procedure

Set v_n solution of

$$\begin{cases} \frac{\partial v_n}{\partial t}(t, x) = -\mathcal{L}v_n(t, x) + \psi(\nabla v_n(t, x) \sqrt{Q}), & t \in [0, T], x \in H \\ v_n(T, x) = \phi_n(x), \end{cases}$$

ϕ_n inf-sup convolution of ϕ .

$v_n(t, x) = Y_t^{n,t,x}$, $\nabla v_n(t, x) \sqrt{Q} = Z_t^{n,t,x}$, where (Y^n, Z^n) solve.

$$\begin{cases} dY_\tau^{n,t,x} = -\psi(Z_\tau^{n,t,x}) d\tau + Z_\tau^{n,t,x} dW_\tau, \\ Y_T^{n,t,x} = \phi_n(X_T^{t,x}). \end{cases}$$

- As $n \rightarrow +\infty$, $(Y^n, Z^n) \rightarrow (Y, Z)$.
- Show that $Z_t^{t,x} = \nabla v(t, x) \sqrt{Q}$.

Theorem 3 *If A, Q, ψ satisfy the previous assumptions, and if ϕ is bounded and continuous, then the HJB equation admits a unique mild solution.*

controlled state equation

$$\begin{cases} dX_\tau^u = [AX_\tau^u + \sqrt{Q}u_\tau] d\tau + \sqrt{Q}dW_\tau, & \tau \in [t, T] \\ X_t^u = x. \end{cases}$$

cost and value function

$$J(t, x, u) = \mathbb{E} \int_t^T [l(X_s^u) + g(u_s)] ds + \mathbb{E}\phi(X_T^u), \quad J^*(t, x) = \inf_u J(t, x, u).$$

where for some $1 < q \leq 2 \exists R, c > 0$ s. t.

$$0 \leq g(u) \leq c(1 + |u|^q), \quad g(u) \geq c|u|^q \quad \text{for every } u : |u| \geq R.$$

Admissible controls: predictable processes s. t. $\mathbb{E} \int_0^T |u_t|^q dt < +\infty$.

Hamiltonian function $\psi(z) = \inf_u \{g(u) + zu\} \quad \forall z \in H$.

v solution of the corresponding HJB $\Rightarrow J^*(t, x) = v(t, x)$, optimal control is given in feedback form.